

# Measuring a causal effect on a network

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Graphical causality models: trees, Bayesian networks and big data

# Networks and causality

## Setting:

- ▶ each observation is a network with a context
- ▶ observations are i.i.d.
- ▶ an underlying causal model is at play

## Conceptual examples:

- ▶ type A or type B breast cancer
  - each woman has her personal history and characteristics
  - a genomic study of sample tissues yields a gene-interaction network
    - what is the "effect" of type on network?
- ▶ randomized trial of low-calory diet in obese women
  - each woman has her personal history and characteristics
  - one flips a coin to assign either low-calory diet or pseudo-diet
  - after a few months, a genomic study of blood samples yields a gene-interaction network
    - what is the "effect" of diet on network?
- ▶ many more. . . (possibly with continuous "actions" )

# Formalization

Nested settings:

- ▶ statistical model:  $O^1, \dots, O^n \stackrel{\text{iid}}{\sim} P_0 \in \mathcal{M}$ 
  - $O = (W, A, Y)$ : context  $W$ , action  $A$ , **binary** network  $Y$  (**fixed set of  $G$  edges**)
- ▶ causal model:  $X = (W, A, Y_0, Y_1) \sim \mathbb{P}_0 \in \mathbb{M}$ 
  - $(Y_0, Y_1, A)$  mutually conditionally independent given  $W$
  - defining  $Y \equiv Y_A$  yields  $O = (W, A, Y) \sim P_0$
  - $P_0$  is a deterministic function of  $\mathbb{P}_0$

Parameters:

- ▶ causal parameter: say  $\Phi : \mathbb{M} \rightarrow [0; 1]$ ,

$$\Phi(\mathbb{P}) = E_{\mathbb{P}}\{\|Y_1 - Y_0\|^2\}$$

- notation:  $\langle u, v \rangle = \frac{1}{G(G-1)} \sum_{1 \leq k < l \leq G} u_{kl} v_{kl}$ ,  $\|u\|^2 = \langle u, u \rangle$

- ▶ *associated* statistical parameter:  $\Psi : \mathcal{M} \rightarrow [0; 1]$ ,

$$\Psi(P) = E_P\{\langle \theta_P(1, W) + \theta_P(0, W) - 2\theta_P(1, W)\theta_P(0, W), \mathbf{1} \rangle\}$$

- notation:  $\theta_P(A, W) = E_P(Y|A, W)$ ,  $g_P(W) = P(A = 1|W)$

**identifiability:**  $\Psi(P_0) = \Phi(\mathbb{P}_0)$ !

## Analysis of $\Psi$

$\Psi$  is pathwise-differentiable at every  $P \in \mathcal{M}$  wrt  $L_0^2(P)$

its efficient influence curve satisfies  $\nabla_P \Psi(O) = \langle \overrightarrow{\nabla_P \Psi}(O), \mathbf{1} \rangle$ , where

$$\begin{aligned} \overrightarrow{\nabla_P \Psi}(O) &= [\theta_P(1, W) + \theta_P(0, W) - 2\theta_P(1, W) * \theta_P(0, W) - \Psi(P)] \\ &\quad + \frac{A}{g_P(W)} (Y - \theta_P(1, W)) * (1 - 2\theta_P(0, W)) \\ &\quad + \frac{1 - A}{1 - g_P(W)} (Y - \theta_P(0, W)) * (1 - 2\theta_P(1, W)) \end{aligned}$$

$\nabla_P \Psi$  conveys crucial information on  $\Psi$ , e.g.

- Cramér-Rao bound:

$\text{Var}_P(\nabla_P \Psi(O))$  is the smallest asymptotic variance of a regular estimator of  $\Psi(P)$  under  $P$

- robustness:

if  $E_P\{\nabla_{P'} \Psi(O)\} = 0$  and either  $g_P = g_{P'}$  or  $\theta_P = \theta_{P'}$  then  $\Psi(P') = \Psi(P)$

$\nabla_P \Psi$  can drive the elaboration of a **targeted** SP inference procedure

# Targeted SP inference procedure

## Targeted minimum loss estimation (TMLE):

- ▶ coined by van der Laan and Rubin [2006]
  - studied, refined/applied in/to many different settings and problems [van der Laan & Rose, 2011]
- ▶ SP-based methodology
  - parenthood with *estimating equations methodology*, *Huber one-step inference*
  - huge body of literature [Robins, 1980-...; Bickel et al., 1993; van der Vaart, 1998]

## Roadmap:

### 1. initialization:

- estimate  $\theta_{P_0}$ ,  $g_{P_0}$ , and  $P_{0,W}$  (with  $\theta_n^0$ ,  $g_n^0$  and empirical measure)
- choose any  $P_n^0$  such that  $\theta_{P_n^0} = \theta_n^0$ ,  $g_{P_n^0} = g_n^0$  and  $P_{n,W}^0 = P_{n,W}$
- set  $k \leftarrow 0$

### 2. iterative updates: while criterion not met, repeat

- 2.1 define  $\frac{dP_n^k(\varepsilon)}{dP_n^k} = 1 + \langle \nabla_{P_n^k} \Psi, \varepsilon \rangle$
- 2.2 compute MLE of  $\varepsilon$ :  $\varepsilon_n^k = \arg \max_{\varepsilon} P_n \log P_n^k(\varepsilon)$
- 2.3 set  $P_n^{k+1} = P_n^k(\varepsilon_n^k)$  and  $k \leftarrow k + 1$

### 3. at final step $k = K_n$ , define TMLE $\psi_n^* = \Psi(P_n^{K_n})$

## Typical theoretical results

**Consistency:** under empirical processes typical conditions

- ▶ if either  $\theta_{P_n^{K_n}}$  or  $g_{P_n^{K_n}}$  converges to the truth then  $\psi_n^*$  consistently estimates  $\Psi(P_0)$

**Central limit theorem:** (same as above)

- ▶ if either  $\theta_{P_n^{K_n}}$  or  $g_{P_n^{K_n}}$  converges to the truth  
and if the product of errors is  $O_P(1/\sqrt{n})$  then  $\psi_n^*$  satisfies a CLT
- ▶ if, in addition, the estimation of  $g_{P_0}$  relies on valid parametric model  
then one can conservatively estimate the asymptotic variance of  $\psi_n^*$

# MovieLens

**Acknowledgement:** GroupLens Research (University of Minnesota), public data set online

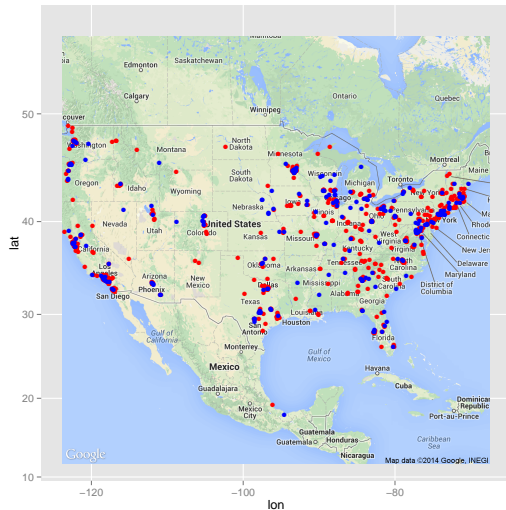
MovieLens: (from the website)

“**MovieLens** is a movie recommendation website. It uses your ratings to generate personalized recommendations for other movies you will like and dislike, based on . . .”

Building a data set:

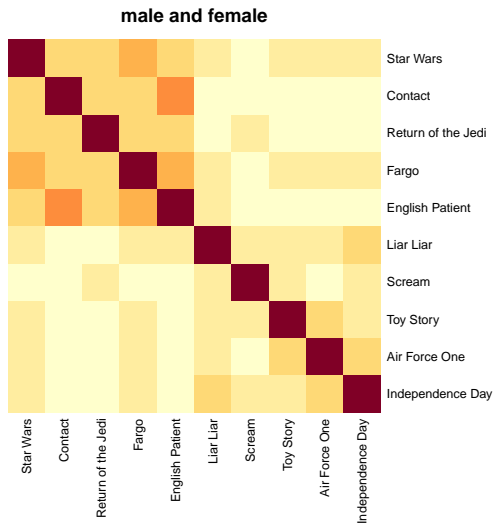
- ▶  $W$ , user information (age, occupation, location)
- ▶  $A$ , gender – **why not, this is a toy example**
- ▶  $Y$ 
  - restriction to the 10 most rated movies
  - $Y \in \mathbb{R}^{45}$ ,  $Y_{ij} = 1$  iff movies  $i$  and  $j$  equally rated by user
  - I create a rate 0 (“unrated”) so that the network is always well-defined
  - sample size  $n = 904$

# MovieLens: whereabouts and gender of users

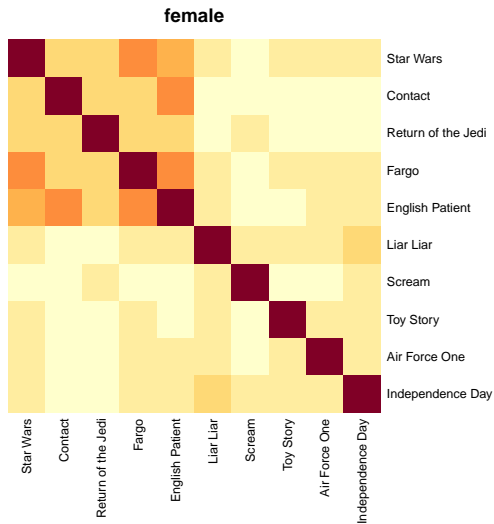




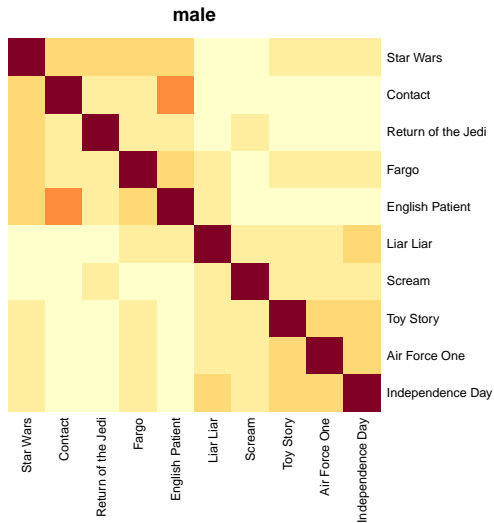
MovieLens:  $E_{P_n}\{Y\}$



MovieLens:  $E_{P_n}(Y|A=0)$



MovieLens:  $E_{P_n}(Y|A=1)$



## Method

- initialization based on *stacked logistic regressions*
- stopping criterion: two successive  $L^2$ -norms of  $\varepsilon_n^k$  smaller than a threshold
- brief summary:
  - $\|\varepsilon_n^k\|_2^2$ : 0.13591, 0.00205, 0.00231
  - $\psi_n^k$ : 0.193, 0.193, 0.197, **0.196**

## Discussion

### Computational/theoretical challenges. . .

- ▶ cope with
  - larger network, large-dimensional contexts
  - strong dependence structure in conditional law of network given action and context
- ▶ elaborate third-order expansions of  $\psi_n^* - \Psi(P_0)$  to derive CLTs that are valid under milder assumptions  
(already done in simpler frameworks, see [van der Laan, 2014])
- ▶ extend to time-evolving networks (still on fixed set of edges),  
e.g. by relying on an auto-regressive **working** model

### Real-life relevant problems, because

- ▶ that would help to come up with a nice simulation scheme
- ▶ that always gives insight
- ▶ that matters